

Stabilizing discontinuous Galerkin schemes. Applications to Shallow-Water equations.

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Subject

Finite-Volume subcell correction
for discontinuous Galerkin schemes.
Applications to Shallow-Water equations.

Goals.

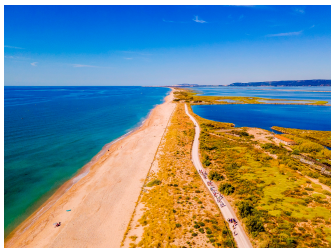
- Studying high-order discontinuous Galerkin schemes;
- Stabilizing numerical schemes using an *a priori* correction;
- Theoretical study of Shallow-Water equations.

Outline of the presentation

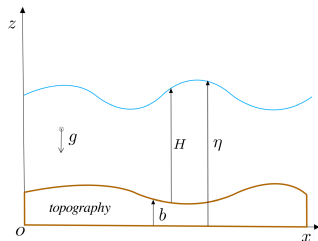
- 1 Shallow-Water equations
 - Benefits of the model
 - Mathematical formulation
- 2 High-order discontinuous Galerkin schemes
 - Overview and advantages
 - Limits for hyperbolic and non-linear equations
- 3 Finite-Volume subcell correction
 - Reformulating dG as FV-like
 - *A posteriori* & *a priori* approaches
- 4 Stabilization of Shallow-Water equations
 - Subcell formulation and water-height positivity
 - Internship continuation and Ph.D. goals

I. Shallow-Water equations

Benefits of Shallow-Water model



(a) Grau du Roi's coastline.



(b) Shallow-Water notations.

- Used mainly in oceanography, hydrology and fluid mechanics;
- Derived from more complex Navier-Stokes equations;
- Allow efficient big-scale simulations in real time.

Pre-balanced formulation

First-order hyperbolic system with source term :

$$\begin{aligned} \partial_t \mathbf{v} + \partial_x F(\mathbf{v}, b) &= \mathbf{B}(\mathbf{v}, \partial_x b) \\ \Leftrightarrow \begin{cases} \partial_t \eta + \partial_x q = 0, \\ \partial_t q + \partial_x \left(uq + \frac{g(\eta^2 - 2\eta b)}{2} \right) = -g\eta \partial_x b. \end{cases} \end{aligned}$$

- $b : \mathbb{R} \rightarrow \mathbb{R}$ is the *topography* parametrization ;
- $\mathbf{v} : \mathbb{R} \times \mathbb{R}_+ \rightarrow \Theta$ is the vector gathering *total elevation* η and *discharge* q , with $\Theta = \{(\eta, q) \in \mathbb{R}^2 \mid H := \eta - b \geq 0\}$;
- $F : \Theta \times \mathbb{R} \rightarrow \mathbb{R}^2$ is the nonlinear flux function ;
- $B : \Theta \times \mathbb{R} \rightarrow \mathbb{R}^2$ is the source term depending on topography.

→ Theoretical derivation of Shallow-Water from incompressible Euler equations.

II. Discontinuous Galerkin schemes

Overview of dG schemes and advantages

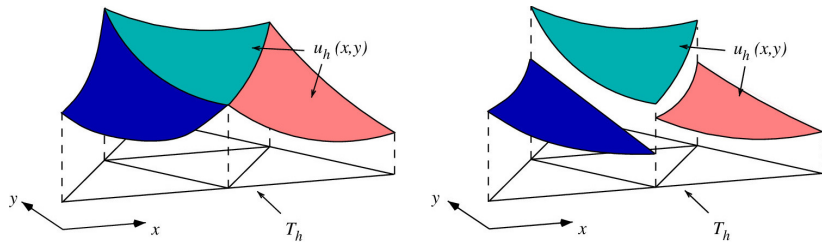


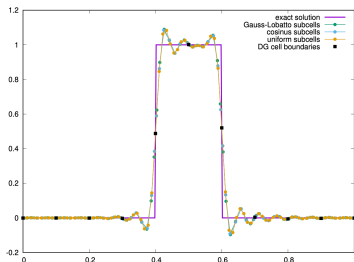
Figure: Continuous and discontinuous Galerkin methods.

- High-order schemes, well-adapted to unstructured meshes;
- Applied to various problems, including hyperbolic PDEs;
- Local formulation interesting for parallel computing.

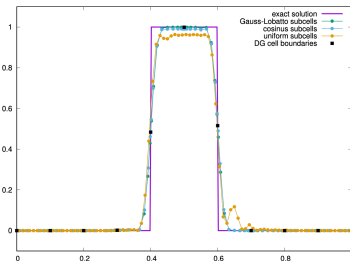
→ Development *from scratch* of a simple C++ program for solving scalar conservation laws using high-order dG (available on Git).

Limits for hyperbolic and non-linear equations

- ⚠ Presence of non-physical oscillations when approaching discontinuities or strong gradients, leading to :
- Non preservation of maximum principle;
 - Loss of water height positivity in Shallow-Water context.



(a) Without correction.



(b) With FVS correction.

Figure: Numerical solution of $\partial_t u + c \partial_x u = 0$, with $u_0(x, t) := \mathbf{1}_{[0.4, 0.6]}$.

III. Finite-Volume subcell correction

Principle

Goals. Refine the geometry by **dividing each cell into subcells**, and use *first-order Finite-Volume* scheme in order to handle the robustness issues.

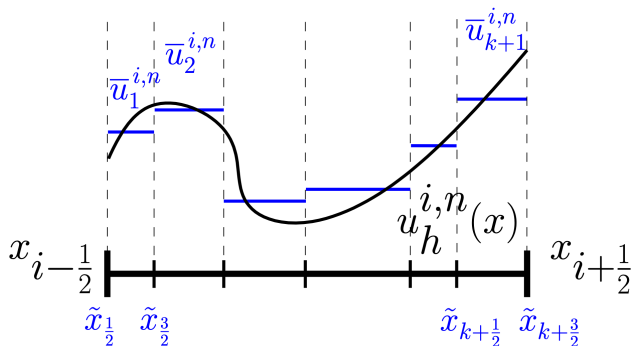


Figure: Sub-mean values on cell $\omega_i = [x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}]$.

Reformulating dG as FV-like on SCL

Needs. Reformulating dG schemes as *Finite-Volume like* schemes at subcell scale using sub-mean values, i.e. the formulation on cell ω_i

$$\int_{\omega_i} \varphi \partial_t \bar{u}_h^{\omega_i} dx = \int_{\omega_i} f(u_h^{\omega_i}) \partial_x \varphi dx - [\mathcal{F} \varphi]_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}}, \quad \forall \varphi \in \mathbb{P}^k(\omega_i),$$

gives us the local formulations on subcells $S_m^{\omega_i}$

$$\partial_t \bar{u}_m^{\omega_i} = -\frac{1}{|S_m^{\omega_i}|} \left(\widehat{F}_{m+\frac{1}{2}}^{\omega_i} - \widehat{F}_{m-\frac{1}{2}}^{\omega_i} \right), \quad \forall m \in \llbracket 1, k+1 \rrbracket,$$

where the $k+2$ *reconstructed fluxes* $\widehat{F}_{m+\frac{1}{2}}^{\omega_i}$ are defined by

$$\begin{aligned} \widehat{F}_{m+\frac{1}{2}}^{\omega_i} &= f_h^{\omega_i}(\tilde{x}_{m+\frac{1}{2}}^{\omega_i}) - C_{m+\frac{1}{2}}^{i-\frac{1}{2}} \left(f_h^{\omega_i}(x_{i-\frac{1}{2}}) - \mathcal{F}_{i-\frac{1}{2}} \right) \\ &\quad - C_{m+\frac{1}{2}}^{i+\frac{1}{2}} \left(f_h^{\omega_i}(x_{i+\frac{1}{2}}) - \mathcal{F}_{i+\frac{1}{2}} \right). \end{aligned}$$

A *posteriori* approach

- Introduced on Shallow-Water during Ali Haidar's PhD;
- Replacing reconstructed fluxes with 1st order FV flux on non-admissible subcells.

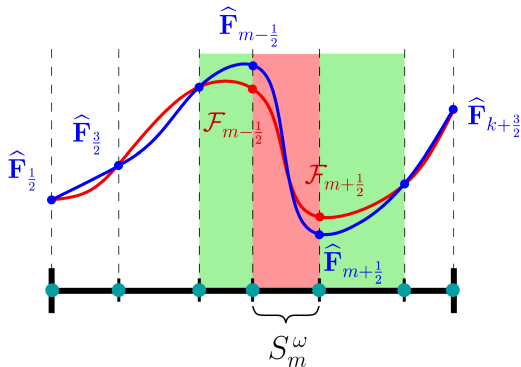


Figure: A *posteriori* correction on subcell $S_m^\omega \subset \omega$.

A priori approach

Goal. Combining reconstructed fluxes with 1st order FV flux, i.e. introducing the following blended fluxes :

$$\tilde{F}_{m\pm\frac{1}{2}}^{\omega_i} = F_{m\pm\frac{1}{2}}^{*,FV} + \theta_{m\pm\frac{1}{2}} \left(\hat{F}_{m\pm\frac{1}{2}}^{\omega_i} - F_{m\pm\frac{1}{2}}^{*,FV} \right),$$

with $\theta_{m\pm\frac{1}{2}} \in [0, 1]$ the coefficient assuring at local scale any convex property we want (entropy, preservation of maximum principle, water height positivity for Shallow-Water ...)

→ Theoretical proofs for preserving maximum principle.

Benefits.

- Simpler implementation opening the method to more people;
- No need to modify the neighbors of non-admissible cells, unlike a *posteriori* approach.

IV. Stabilization of Shallow-Water equations

Preservation of water-height positivity


For $m \in \llbracket 1, k + 1 \rrbracket$ the following NSW dG formulation :

$$\int_{\omega} \partial_t \mathbf{v}_{\omega} \phi_m^{\omega} = - \int_{\omega} \partial_x \mathbf{F}_{\omega} \phi_m^{\omega} + \int_{\omega} \mathbf{B}_{\omega} \phi_m^{\omega} + [\phi_m^{\omega} (\mathbf{F}_{\omega} - \mathcal{F})]_{\partial\omega},$$

can be written as the *FV like* scheme on subcells :

$$\partial_t \bar{\mathbf{v}}_{\omega} = - \frac{1}{|S_m^{\omega}|} \left(\tilde{\mathbf{F}}_{m+\frac{1}{2}}^{\omega} - \tilde{\mathbf{F}}_{m-\frac{1}{2}}^{\omega} \right) + \bar{\mathbf{B}}_m,$$

with $\tilde{\mathbf{F}}_{m+\frac{1}{2}}^{\omega} := \mathbf{F}_{m+\frac{1}{2}}^{*,FV} + \Theta_{m+\frac{1}{2}} \left(\hat{\mathbf{F}}_{m+\frac{1}{2}}^{\omega} - \mathbf{F}_{m+\frac{1}{2}}^{*,FV} \right)$.

 In order to use our stabilization method on Shallow-Water equations, we need to ensure that $\Theta_{m+\frac{1}{2}} = \text{diag}(\theta_{m+\frac{1}{2}}^n, \theta_{m+\frac{1}{2}}^q)$ assure the preservation of water-height positivity and maximum principle → **Theoretical proofs on intermediate Riemann states.**

Internship continuation and Ph.D. goals

Internship continuation. Implementing the *a priori* stabilization method in my homemade C++ code for scalar conservation law and in WaveBox for Shallow-Water equations.

Long term goals. Pursuing in Ph.D. to :

- Construct theoretical model for coupling those equations with a floating object in two dimension;
- Develop and implement the *a priori* correction for this problem and handle the coupling using an Arbitrary Lagrangian Eulerian (ALE) description.

Applications. Renewable energy, notably wave energy converters modeling and optimization.



Figure: *The Great Wave of Kanagawa*, Hokusai, 1830.

Thank you for your attention !